

# Coupled Fixed Point Results In G-Metric Spaces For $W^*$ -Compatible Mappings

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**Abstract:** In this paper, we consider a new class of pairs of generalized contractive type mappings defined in  $G$  – metric spaces. Some coincidence and common fixed point results for these mapping are presented.

**Keywords:** Coincidence Point, Coupled Fixed Point, Common Coupled Fixed Point, Common Fixed Point,

Generalized Metric Space,  $W^*$ -Compatible Mappings.

## 1. Introduction and Preliminaries

Mustafa and Sims [5] introduced the notion of complete  $G$  – metric spaces as a generalization of complete metric spaces. For details on  $G$  – metric spaces, we refer to [5, 6, 7, 8]. The notion of a coupled fixed point in partially ordered metric spaces has been introduced by Bhaskar and Lakshmikantham in (2006)[9]. In this paper ,we prove a common coupled fixed point theorem for two mappings in  $G$  – metric spaces.

**Definition 1.1** [5] Let  $X$  be a nonempty set and  $G: X \times X \times X \rightarrow \mathbb{R}^+$  a function satisfying the following properties:

$$(G_1) \quad G(x, y, z) = 0 \text{ if } x = y = z = 0,$$

$$(G_2) \quad 0 < G(x, x, y), \text{ for all } x, y \in X \text{ with } x \neq y,$$

$$(G_3) \quad G(x, x, y) \leq G(x, y, z) \text{ for all } x, y, z \in X \text{ with } z \neq y,$$

$$(G_4) \quad G(x, y, z) = G(x, z, y) = G(y, z, x) = \dots, \text{ symmetry in all three variables,}$$

$$(G_5) \quad G(x, y, z) \leq G(x, a, a) + G(a, y, z) \text{ for all } x, y, z, a \in X$$

Then the function  $G$  is called a generalized metric, or, more specifically, a  $G$  – metric on  $X$ , and the pair  $(X, G)$  is called a  $G$  – metric space.

**Definition 1.2** [5] Let  $(X, G)$  be a  $G$  – metric space and  $(x_n)$  a sequence of points of  $X$ . A point  $x \in X$  is said to be the limit of the sequence  $(x_n)$ , if  $\lim_{m, n \rightarrow \infty} G(x, x_n, x_m) = 0$ , and we say that the sequence  $(x_n)$  is  $G$  – convergent to  $x$  or that  $(x_n)$   $G$  – converges to  $x$ .

Thus,  $x_n \rightarrow x$  in a  $G$  – metric space  $(X, G)$  if for any  $\varepsilon > 0$ , there exists  $k \in \mathbb{N}$  such that

$G(x, x_n, x_m) < \varepsilon$  for all  $m, n \geq k$ .

**Proposition 1.1.** [5] Let  $(X, G)$  be a  $G$ -metric space. Then the following are equivalent:

- (1)  $(x_n)$  is  $G$ -convergent to  $x$ .
- (2)  $G(x_n, x_n, x) \rightarrow 0$  as  $n \rightarrow \infty$ .
- (3)  $G(x_n, x, x) \rightarrow 0$  as  $n \rightarrow \infty$ .
- (4)  $G(x_n, x_m, x) \rightarrow 0$  as  $n, m \rightarrow \infty$ .

**Definition 1.3** [5] Let  $(X, G)$  be a  $G$ -metric space, a sequence  $(x_n)$  is called  $G$ -Cauchy if for every  $\varepsilon > 0$ , there is  $k \in \mathbb{N}$  such that  $G(x_n, x_m, x_l) < \varepsilon$ , for all  $n, m, l \geq k$ , that is  $G(x_n, x_m, x_l) \rightarrow 0$  as  $n, m, l \rightarrow \infty$ .

**Proposition 1.2.** [5] Let  $(X, G)$  be a  $G$ -metric space, then the following statements are equivalent:

- (1) The sequence  $(x_n)$  is  $G$ -Cauchy.
- (2) For every  $\varepsilon > 0$  there is  $k \in \mathbb{N}$  such that  $G(x_n, x_m, x_m) < \varepsilon$ , for all  $n, m \geq k$ .

**Definition 1.4** [5] A  $G$ -metric space  $(X, G)$  is called  $G$ -complete if every  $G$ -Cauchy sequence in  $(X, G)$  is  $G$ -convergent in  $(X, G)$ .

**Proposition 1.3.** [5] Let  $(X, G)$  be a  $G$ -metric space. Then, the function  $G(x, y, z)$  is jointly continuous in all three of its variables.

**Example 1.1.** [5] Let  $(\mathbb{R}, d)$  be the usual metric space. Define  $G_s$  by

$$G_s(x, y, z) = d(x, y) + d(y, z) + d(x, z)$$

for all  $x, y, z \in \mathbb{R}$ . Then it is clear that  $(\mathbb{R}, G_s)$  is a  $G$ -metric space.

**Proposition 1.4.** [5] Let  $(X, G)$  be a  $G$ -metric space. Then  $T: X \rightarrow X$  is  $G$ -continuous at  $x \in X$  if and only if it is  $G$ -sequentially continuous at  $x$ , that is, whenever  $(x_n)$  is  $G$ -convergent to  $x$ ,  $(f(x_n))$  is  $G$ -convergent to  $f(x)$ .

**Definition 1.5** [4] Let  $(X, G)$  be a  $G$ -metric space. A mapping  $F: X \times X \rightarrow X$  is said to be

continuous if for any two  $G$ -convergent sequences  $(x_n)$  and  $(y_n)$  converging to  $x$  and  $y$  respectively,  $(F(x_n, y_n))$  is  $G$ -convergent to  $F(x, y)$ .

**Definition 1.6** [3] An element  $(x, y) \in X \times X$  is called a coupled fixed point of the mapping

$$F : X \times X \rightarrow X \text{ if } F(x, y) = x, F(y, x) = y.$$

**Definition 1.7** [9] An element  $(x, y) \in X \times X$  is called a coupled coincidence point of a mapping

$$F : X \times X \rightarrow X \text{ and a mapping } g : X \rightarrow X \text{ if } F(x, y) = gx, F(y, x) = gy.$$

Note that if  $g$  is the identity mapping, then Definition 1.7 reduces to Definition 1.6.

**Definition 1.8** [1] An element  $x \in X$  is called a common fixed point of a mapping  $F : X \times X \rightarrow X$  and  $g : X \rightarrow X$  if  $F(x, x) = gx = x$ .

Abbas et al. [1] introduced the concept of  $w$ -compatible and  $w^*$ -compatible mappings and utilized this concept to prove an interesting uniqueness theorem of a coupled fixed point for mappings  $F$  and  $g$  in cone metric spaces.

**Definition 1.9** [1] Mappings  $F : X \times X \rightarrow X$  and  $g : X \rightarrow X$  are called

$$(w_1) \text{ } w\text{-compatible if } g(F(x, y)) = F(gx, gy) \text{ whenever } gx = F(x, y) \text{ and } gy = F(y, x).$$

$$(w_2) \text{ } w^*\text{-compatible if } g(F(x, x)) = F(gx, gx) \text{ whenever } gx = F(x, x).$$

**Example 1.2.** [2] Let  $X = \mathbb{R}^+$ , define  $F : X \times X \rightarrow X$  and  $g : X \rightarrow X$  by

$$F(x, y) = \begin{cases} 8, & x = 1, y = 0, \\ 10, & x = 0, y = 1, \\ 4 & \text{other wise,} \end{cases} \text{ and } g(x) = \begin{cases} 8, & x = 1, \\ 10, & x = 0, \\ 5, & x = 4, \\ 4, & \text{other wise.} \end{cases}$$

Then it is clear that  $F$  and  $g$  are  $w$ -compatible but not  $w^*$ -compatible.

**Definition 1.10** [9] Let  $X$  be a nonempty set and  $F : X \times X \rightarrow X$  and  $g : X \rightarrow X$ . One says  $F$

and  $g$  are commutative if for all  $x, y \in X$ ,  $F(gx, gy) = g(F(x, y))$ .

## 2. Main results

Our first result is the following.

**Theorem 2.1** Let  $(X, G)$  be a  $G$ -metric space. Set  $T : X \times X \rightarrow X$  and  $g : X \rightarrow X$ . Assume

there exist  $a_1, a_2, a_3 \geq 0$  with  $2a_1 + 3a_2 + 3a_3 < 2$  such that

$$\begin{aligned} G(T(x, y), T(u, v), T(w, z)) &\leq \frac{a_1}{2} [G(gx, gu, gw) + G(gy, gv, gz)] \\ &+ \frac{a_2}{2} [G(gx, T(x, y), T(x, y)) + G(gu, T(u, v), T(u, v)) + G(gy, gv, gz)] \\ &+ \frac{a_3}{2} [G(gx, T(u, v), T(u, v)) + G(gu, T(x, y), T(x, y)) + G(gy, gv, gz)], \end{aligned} \quad (2.1)$$

for all  $x, y, u, v, w, z \in X$ . If  $T(X \times X) \subseteq g(X)$ ,  $g(X)$  is a  $G$ -complete subset of  $X$ , then  $T$  and  $g$  have a unique common coupled coincidence point. Moreover, if  $T$  is  $w^*$ -compatible with  $g$ , then  $T$  and  $g$  have a unique common coupled fixed point.

**Proof.** Let  $x_0$  and  $y_0$  be in  $X$ . Since  $T(X \times X) \subseteq g(X)$ , we can choose  $x_1, y_1 \in X$  such that  $gx_1 = T(x_0, y_0)$  and  $gy_1 = T(y_0, x_0)$ . Analogously, there exist  $x_2, y_2 \in X$  such that  $gx_2 = T(x_1, y_1)$  and  $gy_2 = T(y_1, x_1)$ . Continuing this process, we can construct two sequences  $\{x_n\}$  and  $\{y_n\}$  in  $X$  such that

$$gx_{n+1} = T(x_n, y_n) \text{ and } gy_{n+1} = T(y_n, x_n) \text{ for all } n \geq 0 \quad (2.2)$$

From by (2.1), we have

$$\begin{aligned} G(gx_n, gx_{n+1}, gx_{n+1}) &= G(T(x_{n-1}, y_{n-1}), T(x_n, y_n), T(x_n, y_n)) \\ &\leq \frac{a_1}{2} [G(gx_{n-1}, gx_n, gx_n) + G(gy_{n-1}, gy_n, gy_n)] \\ &+ \frac{a_2}{2} [G(gx_{n-1}, T(x_{n-1}, y_{n-1}), T(x_{n-1}, y_{n-1})) + G(gx_n, T(x_n, y_n), T(x_n, y_n))] + \\ &G(gy_{n-1}, gy_n, gy_n) + \frac{a_3}{2} [G(gx_{n-1}, T(x_n, y_n), T(x_n, y_n)) \\ &+ G(gx_n, T(x_{n-1}, y_{n-1}), T(x_{n-1}, y_{n-1})) + G(gy_{n-1}, gy_n, gy_n)] \\ &= \frac{a_1}{2} [G(gx_{n-1}, gx_n, gx_n) + G(gy_{n-1}, gy_n, gy_n)] \\ &+ \frac{a_2}{2} [G(gx_{n-1}, gx_n, gx_n) + G(gx_n, gx_{n+1}, gx_{n+1}) + G(gy_{n-1}, gy_n, gy_n)] \\ &+ \frac{a_3}{2} [G(gx_{n-1}, gx_{n+1}, gx_{n+1}) + G(gx_n, gx_n, gx_n) + G(gy_{n-1}, gy_n, gy_n)]. \end{aligned}$$

Thus, we obtain

$$G(gx_n, gx_{n+1}, gx_{n+1}) \leq \frac{a_1 + a_2 + a_3}{2 - a_2 - a_3} [G(gx_{n-1}, gx_n, gx_n) + G(gy_{n-2}, gy_{n-1}, gy_{n-1})], \quad (2.3)$$

and

$$\begin{aligned}
 G(gy_n, gy_{n+1}, gy_{n+1}) &= G(T(y_{n-1}, x_{n-1}), T(y_n, x_n), T(y_n, x_n)) \\
 &\leq \frac{a_1}{2} [G(gy_{n-1}, gy_n, gy_n) + G(gx_{n-1}, gx_n, gx_n)] \\
 &+ \frac{a_2}{2} [G(gy_{n-1}, T(y_{n-1}, x_{n-1}), T(y_{n-1}, x_{n-1})) + G(gy_n, T(y_n, x_n), T(y_n, x_n)) \\
 &\quad + G(gx_{n-1}, gx_n, gx_n)] + \frac{a_3}{2} [G(gy_{n-1}, T(y_n, x_n), T(y_n, x_n)) \\
 &\quad + G(gy_n, T(y_{n-1}, x_{n-1}), T(y_{n-1}, x_{n-1})) + G(gx_{n-1}, gx_n, gx_n)] \\
 &= \frac{a_1}{2} [G(gy_{n-1}, gy_n, gy_n) + G(gx_{n-1}, gx_n, gx_n)] \\
 &+ \frac{a_2}{2} [G(gy_{n-1}, gy_n, gy_n) + G(gy_n, gy_{n+1}, gy_{n+1}) + G(gx_{n-1}, gx_n, gx_n)] \\
 &+ \frac{a_3}{2} [G(gy_{n-1}, gy_{n+1}, gy_{n+1}) + G(gy_n, gy_n, gy_n) + G(gx_{n-1}, gx_n, gx_n)].
 \end{aligned}$$

Thus, we obtain

$$G(gy_n, gy_{n+1}, gy_{n+1}) \leq \frac{a_1 + a_2 + a_3}{2 - a_2 - a_3} [G(gy_{n-1}, gy_n, gy_n) + G(gx_{n-1}, gx_n, gx_n)]. \quad (2.4)$$

From (2.3) and (2.4), we have

$$G(gx_n, gx_{n+1}, gx_{n+1}) + G(gy_n, gy_{n+1}, gy_{n+1}) \leq \frac{2(a_1 + a_2 + a_3)}{2 - a_2 - a_3} [G(gy_{n-1}, gy_n, gy_n) + G(gx_{n-1}, gx_n, gx_n)].$$

Set  $a_n = G(gx_n, gx_{n+1}, gx_{n+1}) + G(gy_n, gy_{n+1}, gy_{n+1})$  and  $\lambda = \frac{2(a_1 + a_2 + a_3)}{2 - a_2 - a_3}$ , then the

sequence  $\{a_n\}$  is decreasing as

$$0 \leq a_n \leq \lambda a_{n-1} \leq \lambda^2 a_{n-2} \leq \dots \leq \lambda^n a_0$$

which implies

$$\lim_{n \rightarrow \infty} a_n = \lim_{n \rightarrow \infty} [G(gx_n, gx_{n+1}, gx_{n+1}) + G(gy_n, gy_{n+1}, gy_{n+1})] = 0.$$

Thus,

$$\lim_{n \rightarrow \infty} G(gx_n, gx_{n+1}, gx_{n+1}) = 0, \quad \text{and} \quad \lim_{n \rightarrow \infty} G(gy_n, gy_{n+1}, gy_{n+1}) = 0. \quad (2.5)$$

Next, let us prove that  $\{gx_n\}$  and  $\{gy_n\}$  are  $G$ -Cauchy sequences. In fact, for  $m > n$ , we have

$$\begin{aligned}
 G(gx_n, gx_m, gx_m) + G(gy_n, gy_m, gy_m) &\leq G(gx_n, gx_{n+1}, gx_{n+1}) + G(gy_n, gy_{n+1}, gy_{n+1}) \\
 &\quad + G(gx_{n+1}, gx_{n+2}, gx_{n+2}) + G(gy_{n+1}, gy_{n+2}, gy_{n+2})
 \end{aligned}$$

$$\begin{aligned}
 &+ \dots + G(gx_{m-1}, gx_m, gx_m) + G(gy_{m-1}, gy_m, gy_m) \\
 &= a_n + a_{n+1} + \dots + a_{m-1} \\
 &\leq \lambda^n a_0 + \lambda^{n+1} a_0 + \dots + \lambda^{m-1} a_0 = (\lambda^n + \lambda^{n+1} + \dots + \lambda^{m-1}) a_0 \\
 &\leq \frac{\lambda^n}{1 - \lambda} a_0.
 \end{aligned}$$

Letting  $n, m \rightarrow \infty$ , we have

$$\lim_{n, m \rightarrow \infty} G(gx_n, gx_m, gx_m) + G(gy_n, gy_m, gy_m) = 0.$$

This imply that  $\{gx_n\}$  and  $\{gy_n\}$  are  $G$ -Cauchy sequences in  $g(X)$ . By  $G$ -completeness of  $g(X)$ , there exists  $gx, gy \in g(X)$  such that  $\{gx_n\}$  and  $\{gy_n\}$  converge to  $gx$  and  $gy$ , respectively. We claim that  $g(x) = T(x, y)$  and  $g(y) = T(y, x)$ . Indeed, from (2.1), we have

$$\begin{aligned}
 G(gx_{n+1}, T(x, y), T(x, y)) &= G(T(x_n, y_n), T(x, y), T(x, y)) \\
 &\leq \frac{a_1}{2} [G(gx_n, g(x), g(x)) + G(gy_n, g(y), g(y))] \\
 &+ \frac{a_2}{2} [G(gx_n, T(x_n, y_n), T(x_n, x_n)) + G(g(x), T(x, y), T(x, y)) \\
 &+ G(gy_n, g(y), g(y))] + \frac{a_3}{2} [G(gx_n, T(x, y), T(x, y)) \\
 &+ G(g(x), T(x_n, y_n), T(x_n, y_n)) + G(gy_n, g(y), g(y))]
 \end{aligned}$$

Letting  $n \rightarrow \infty$ , and using the fact that  $G$  is continuous on its variables, we get that

$$G(g(x), T(x, y), T(x, y)) \leq \frac{a_2 + a_3}{2} G(g(x), T(x, y), T(x, y)).$$

Hence  $g(x) = T(x, y)$ . Similarly, we may show that  $g(y) = T(y, x)$ . Then,  $(gx, gy)$  is a coupled point of coincidence of mappings  $T$  and  $g$ . Now we prove that  $gx = gy$ . By (2.1), we have

$$\begin{aligned}
 G(g(x), g(y), g(y)) &= G(T(x, y), T(y, x), T(y, x)) \\
 &\leq \frac{a_1}{2} [G(g(x), g(y), g(y)) + G(g(y), g(x), g(x))] \\
 &+ \frac{a_2}{2} [G(g(x), T(x, y), T(x, y)) + G(g(y), T(y, x), T(y, x)) + G(g(y), g(x), g(x))] \\
 &+ \frac{a_3}{2} [G(g(x), T(y, x), T(y, x)) + G(g(y), T(x, y), T(x, y)) + G(g(y), g(x), g(x))]
 \end{aligned}$$

$$= \frac{a_1 + a_3}{2} G(g(x), g(y), g(y)) + \frac{a_1 + a_2 + 2a_3}{2} G(g(y), g(x), g(x)).$$

Similarly, we may show that

$$G(g(y), g(x), g(x)) \leq \frac{a_1 + a_2 + 2a_3}{2} G(g(x), g(y), g(y)) + \frac{a_1 + a_3}{2} G(g(y), g(x), g(x)).$$

Therefore

$$\begin{aligned} G(g(x), g(y), g(y)) + G(g(y), g(x), g(x)) &\leq \frac{2a_1 + a_2 + 3a_3}{2} [G(g(x), g(y), g(y)) + G(g(y), g(x), g(x))] \\ &< G(g(x), g(y), g(y)) + G(g(y), g(x), g(x)). \end{aligned}$$

which is a contradiction. So  $g(x) = g(y)$ . We conclude that  $T(x, y) = g(x) = g(y) = T(y, x)$ .

Thus,  $(g(x), g(x))$  is a coupled point of coincidence of mappings  $T$  and  $g$ . Now, if there is another

$x_1 \in X$  such that  $(g(x_1), g(x_1))$  is a coupled point of coincidence of mappings  $T$  and  $g$ , then

$$\begin{aligned} G(g(x), g(x_1), g(x_1)) &= G(T(x, x), T(x_1, x_1), T(x_1, x_1)) \\ &\leq \frac{a_1}{2} [G(g(x), g(x_1), g(x_1)) + G(g(x), g(x_1), g(x_1))] \\ &+ \frac{a_2}{2} [G(g(x), T(x, x), T(x, x)) + G(g(x), T(x_1, x_1), T(x_1, x_1)) + G(g(x), g(x_1), g(x_1))] \\ &+ \frac{a_3}{2} [G(g(x), T(x_1, x_1), T(x_1, x_1)) + G(g(x_1), T(x, x), T(x, x)) + G(g(x), g(x_1), g(x_1))] \\ &= (a_1 + a_2 + a_3)G(g(x), g(x_1), g(x_1)) + \frac{a_3}{2} G(g(x_1), g(x), g(x)). \end{aligned}$$

Similarly, we may show that

$$G(g(x_1), g(x), g(x)) \leq (a_1 + a_2 + a_3)G(g(x_1), g(x), g(x)) + \frac{a_3}{2} G(g(x), g(x_1), g(x_1)).$$

Therefore

$$G(g(x), g(x_1), g(x_1)) + G(g(x_1), g(x), g(x)) \leq \frac{2a_1 + 2a_2 + 3a_3}{2} [G(g(x), g(x_1), g(x_1)) + G(g(x_1), g(x), g(x))].$$

It implies that  $G(g(x), g(x_1), g(x_1)) = G(g(x_1), g(x), g(x)) = 0$  and so  $g(x) = g(x_1)$ . Hence,

$(g(x), g(x))$  is a unique coupled point of coincidence of mappings  $T$  and  $g$ . Now, we show that  $T$

and  $g$  have common coupled fixed point. For this, let  $u = g(x)$ . Then, we have  $u = g(x) = T(x, x)$ .

By  $w^*$ -compatibility of  $T$  and  $g$ , we have

$$g(u) = g(g(x)) = g(T(x, x)) = T(g(x), g(x)) = T(u, u).$$

Then,  $(g(u), g(u))$  is a coupled point of coincidence of mappings  $T$  and  $g$ . By the uniqueness of

coupled point of coincidence, we have  $g(x) = g(u)$ . Therefore,  $(u, u)$  is the common coupled fixed point of  $T$  and  $g$ . To prove the uniqueness, let  $v \in X$  with  $v \neq u$  such that  $(v, v)$  is the common coupled fixed point of  $T$  and  $g$ . Then, using (2.1),

$$\begin{aligned} G(u, v, v) &= G(T(u, u), T(v, v), T(v, v)) \leq \frac{a_1}{2} [G(gu, gv, gv) + G(gu, gv, gv)] \\ &\quad + \frac{a_2}{2} [G(gu, T(u, u), T(u, u)) + G(gv, T(v, v), T(v, v)) + G(gu, gv, gv)] \\ &\quad + \frac{a_3}{2} [G(gu, T(v, v), T(v, v)) + G(gv, T(u, u), T(u, u)) + G(gu, gv, gv)] \\ &= (a_1 + \frac{a_2}{2} + a_3)G(u, v, v) + \frac{a_3}{2} G(v, u, u). \end{aligned}$$

Similarly, we may show that

$$G(v, u, u) \leq (a_1 + \frac{a_2}{2} + a_3)G(v, u, u) + \frac{a_3}{2} G(u, v, v).$$

Hence,

$$G(u, v, v) + G(v, u, u) \leq \frac{2a_1 + a_2 + 3a_3}{2} [G(u, v, v) + G(v, u, u)].$$

Since  $\frac{2a_1 + a_2 + 3a_3}{2} < 1$ , so that  $G(u, v, v) = G(v, u, u) = 0$  and  $u = v$ . Thus  $T$  and  $g$  have a unique common coupled fixed point. In Theorem 2.1, take  $w = u$  and  $z = v$ , to obtain the following corollary.

**Corollary 2.2** Let  $(X, G)$  be a  $G$ -metric space. Set  $T : X \times X \rightarrow X$  and  $g : X \rightarrow X$ . Assume there exist  $a_1, a_2, a_3 \geq 0$  with  $2a_1 + 3a_2 + 3a_3 < 2$  such that

$$\begin{aligned} G(T(x, y), T(u, v), T(u, v)) &\leq \frac{a_1}{2} [G(gx, gu, gu) + G(gy, gv, gv)] \tag{2.6} \\ &\quad + \frac{a_2}{2} [G(gx, T(x, y), T(x, y)) + G(gu, T(u, v), T(u, v)) + G(gy, gv, gv)] \\ &\quad + \frac{a_3}{2} [G(gx, T(u, v), T(u, v)) + G(gu, T(x, y), T(x, y)) + G(gy, gv, gv)], \end{aligned}$$

for all  $x, y, u, v, w, z \in X$ . If  $T(X \times X) \subseteq g(X)$ ,  $g(X)$  is a  $G$ -complete subset of  $X$ , then  $T$  and  $g$  have a unique common coupled coincidence point. Moreover, if  $T$  is  $w^*$ -compatible with  $g$ , then  $T$  and  $g$  have a unique common coupled fixed point.

Now, putting  $g = I_X$  (the identity map of  $X$ ) in the Theorem 2.1, we obtain

**Corollary 2.3** Let  $(X, G)$  be a complete  $G$ -metric space. Assume  $T : X \times X \rightarrow X$  be a function



satisfying (2.1)(with  $g = I_X$ ) for all  $x, y, u, v, w, z \in X$ . Then  $T$  has a unique fixed point.

By choosing  $a_1, a_2$  and  $a_3$  suitably, one can deduce some corollaries from Theorem 2.1.

For example, if  $a_1 = 2k$  and  $a_2 = a_3 = 0$  in Theorem 2.1, then the following corollary is obtained which extends and generalizes the comparable results of [10].

**Corollary 2.4** Let  $(X, G)$  be a  $G$ -metric space. Set  $T : X \times X \rightarrow X$  and  $g : X \rightarrow X$ . Assume

there exist  $k \in [0, \frac{1}{2})$  such that

$$G(T(x, y), T(u, v), T(w, z)) \leq k[G(gx, gu, gw) + G(gy, gv, gz)], \quad (2.7)$$

for all  $x, y, u, v, w, z \in X$ . If  $T(X \times X) \subseteq g(X)$ ,  $g(X)$  is a  $G$ -complete subset of  $X$ , then  $T$  and  $g$  have a unique common coupled coincidence point. Moreover, if  $T$  is  $w^*$ -compatible with  $g$ , then  $T$  and  $g$  have a unique common coupled fixed point.

Now, we introduce an example to support the usability of our results.

**Example 2.1.** Let  $X = [0, 1]$ . Define  $T : X \times X \rightarrow X$  by  $T(x, y) = \frac{1}{16}x^2y^2$  and define  $g : X \rightarrow X$  by  $g(x) = \frac{1}{2}x^2$ .

Define a  $G$ -metric on  $X$  by  $G(x, y, z) = |x - y| + |x - z| + |y - z|$  for all  $x, y, z \in X$ .

By routine calculations, the reader can easily verify that the following assumptions hold:

- (1)  $T(X \times X) \subseteq g(X)$ ;
- (2)  $g(X)$  is a  $G$ -complete subset of  $X$ ;
- (3)  $T$  is  $w^*$ -compatible with  $g$ .

Here, we show only that  $T$  and  $g$  are condition (2.1) in Theorem 2.1 is satisfied for all real numbers  $a_1, a_2, a_3$  with  $0 \leq 2a_1 + 3a_2 + 3a_3 < 2$ . Since  $|xy - uv| \leq |x - u| + |y - v|$  holds for all  $x, y, u, v \in X$ , we have

$$\begin{aligned} G(T(x, y), T(u, v), T(w, z)) &= G\left(\frac{1}{16}x^2y^2, \frac{1}{16}u^2v^2, \frac{1}{16}w^2z^2\right) \\ &= \frac{1}{16}|x^2y^2 - u^2v^2| + \frac{1}{16}|x^2y^2 - w^2z^2| + \frac{1}{16}|u^2v^2 - w^2z^2| \end{aligned}$$

$$\begin{aligned}
 &\leq \frac{1}{16} [|x^2 - u^2| + |y^2 - v^2| + |x^2 - w^2| + |y^2 - z^2| + |u^2 - w^2| + |v^2 - z^2|] \\
 &\leq \frac{1}{8} [| \frac{1}{2}x^2 - \frac{1}{2}u^2 | + | \frac{1}{2}x^2 - \frac{1}{2}w^2 | + | \frac{1}{2}u^2 - \frac{1}{2}w^2 | + | \frac{1}{2}y^2 - \frac{1}{2}v^2 | + | \frac{1}{2}y^2 - \frac{1}{2}z^2 | + \\
 &\quad | \frac{1}{2}v^2 - \frac{1}{2}z^2 |] + \frac{1}{16} [| \frac{1}{2}x^2 - \frac{1}{16}x^2y^2 | + | \frac{1}{2}u^2 - \frac{1}{16}u^2v^2 | + | \frac{1}{2}y^2 - \frac{1}{2}v^2 | + \\
 &\quad | \frac{1}{2}y^2 - \frac{1}{2}z^2 | + | \frac{1}{2}v^2 - \frac{1}{2}z^2 |] + \frac{1}{16} [| \frac{1}{2}x^2 - \frac{1}{16}u^2v^2 | + | \frac{1}{2}u^2 - \frac{1}{16}x^2y^2 | + \\
 &\quad | \frac{1}{2}y^2 - \frac{1}{2}v^2 | + | \frac{1}{2}y^2 - \frac{1}{2}z^2 | + | \frac{1}{2}v^2 - \frac{1}{2}z^2 |] \\
 &\leq \frac{1}{2} [G(gx, gu, gw) + G(gy, gv, gz)] \\
 &\quad + \frac{8}{2} [G(gx, T(x, y), T(x, y)) + G(gu, T(u, v), T(u, v)) + G(gy, gv, gz)] \\
 &\quad + \frac{8}{2} [G(gx, T(u, v), T(u, v)) + G(gu, T(x, y), T(x, y)) + G(gy, gv, gz)].
 \end{aligned}$$

Thus, (2.1) is satisfied with  $a_1 = \frac{1}{4}$  and  $a_2 = a_3 = \frac{1}{8}$  where  $2a_1 + 3a_2 + 3a_3 < 2$ . Hence, all the conditions of Theorem 2.1 are satisfied. Moreover,  $(0,0)$  is the unique common coupled fixed point of  $T$  and  $g$ . References

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