# Application of Electromagnetic Field Tensors in Special Relativity Theory 

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#### Abstract

Maxwell's Field Equations (MFE's) for the propagation of electromagnetic waves were found to be invariant under Lorentz transformation (LT) and could be derived using assumptions different from what Einstein used. Here, we start with electromagnetic field tensors, obtain the MFE's and apply the relativistic principle to them. With this approach, Special Relativity Theory (SRT) is reformulated in a simple form without using the LT and it's kinematical contradictions. Our results are in agreement with the existing literature.


## KEYWORDS

Maxwell's field equations, Relativity principle, Lorentz and Galilean transformation.

## 1. INTRODUCTION

Galilean relativity shows that the laws of mechanics are the same for a body at rest and a body moving at constant velocity. Newton also developed his laws of motion and his concept of relativity which states that, "the laws of mechanics must be the same in all inertial frames." ${ }^{\text {" }} 1$. Due to Galileo and Newton, the concept of absolute space became redundant but absolute time was retained, the development of electromagnetic theory in the nineteenth century demonstrated a problem with Newtonian relativity. It became inconceivable to physicist that electromagnetic wave could propagate without a medium (the ether) [2]. But as a consequence of Newtonian relativity, an observer moving through the ether with velocity $u$ would measure the velocity the velocity of a light beam as $(c+u)$, hence the Michelson-Morley experiment showed that no ether (absolute reference frame) existed for electromagnetic phenomena [3].

This result opened a way for a new approach which is Einstein relativity [4]. He postulated that the speed of light is invariant in all inertial frames which lead to a new relationship between space and time (Lorentz transformation). MFE's for the propagation of electromagnetic waves were not invariant under Galilean transformation (GT), but were invariant under LT. For invariant under LT we deal with three quantities: space, time and light speed. In Einstein's approach for deriving the LT, he connected the three quantities through a new velocity $v$ along $x$ [5].

$$
\begin{equation*}
v_{x}^{\prime}=\frac{v_{x}}{1-\frac{u v_{x}}{c^{2}}} \tag{1}
\end{equation*}
$$

He used the basic definition for any velocity in frame $S$ or $S^{\prime}$ as:

$$
\begin{equation*}
v_{x}=\frac{d x}{d t} ; \quad v_{x}^{\prime}=\frac{d x^{\prime}}{d t^{\prime}} \tag{2}
\end{equation*}
$$

And his second postulate for light speed as:

$$
\begin{equation*}
\frac{d x}{d t}=\frac{d x^{\prime}}{d t^{\prime}}=c \tag{3}
\end{equation*}
$$

This is understood as the "measurement rule."
For the invariant of light speed, time itself has to slow down and space must contract to give almost the same value in Eq.(3) [6]. Thus Einstein introduced relativity of simultaneity to physics. But the interpretation of LT and it's kinematical effects has long been questioned and misunderstood. Today, paradox [7,8], criticism [9,10] still continue to receive attention, as a result many physicist believe that a new interpretation or even a theory alternative to SRT may be needed [11].
In this research we use electromagnetic field tensors to generate MFE's and apply the relativistic principle to obtain the LT equations. The MFE's stands in place of Einstein's relativity of simultaneity. The LT produced by our alternative method is simply a neutral transformation and it's results are the same as that obtained initially [12, 13].

## 2. ELECTROMAGNETIC FIELD TENSORS

Electromagnetic field tensors is a mathematical objective that describes the electromagnetic field of a physical system[14]. The field tensor was first used after the 4-dimentional tensor formulation of SRT (Minkowski space).
It was known that the 4 -vectors for the electromagnetic field $\vec{E}, \vec{B}$ is represented by the scalar and vector potential $\phi, \vec{A}$ as follows:

$$
\begin{equation*}
\vec{B}=\nabla \times \vec{A} ; \quad \vec{E}=-\nabla \phi-\frac{\partial \vec{A}}{\partial t} \tag{4}
\end{equation*}
$$

$F_{\mu \nu}$ is defined as an antisymmetric rank-2 tensor which is written in terms of 4-dimentional vectors as[15]:

$$
\begin{equation*}
F_{\mu \nu}=\frac{\partial A_{v}}{\partial x^{\mu}}-\frac{\partial A_{\mu}}{\partial x^{v}} ; \quad(\mu \nu=1,2,3,4) \tag{5}
\end{equation*}
$$

Where

$$
\begin{equation*}
x_{v}=(x, y, z, i c t) ; \quad A_{\mu}=\left(A_{x}, A_{y}, A_{z}, \frac{i \phi}{c}\right) \tag{6}
\end{equation*}
$$

We represent this set of equations in a $4 \times 4$ matrix form as;

$$
F_{\mu \nu}=\left[\begin{array}{cccc}
0 & B_{z} & -B_{y} & -\frac{i}{c} E_{x}  \tag{7}\\
-B_{z} & 0 & B_{x} & -\frac{i}{c} E_{y} \\
B_{y} & -B_{x} & 0 & -\frac{i}{c} E_{z} \\
\frac{i}{c} E_{x} & \frac{i}{c} E_{y} & \frac{i}{c} E_{z} & 0
\end{array}\right]
$$

This tensor simplifies and reduces Maxwell equations as 4 -vector calculus equations into 2 -vector field equations. In magnetostatics, Gauss law for magnetism and Maxwell-Faraday's equation are gotten from:

$$
\begin{equation*}
\frac{\partial F_{\alpha \beta}}{\partial x^{\mu}}+\frac{\partial F_{\beta \mu}}{\partial x^{\alpha}}+\frac{\partial F_{\mu \alpha}}{\partial x^{\beta}}=0 ; \quad(\alpha, \beta, \mu=1,2,3,4) \tag{8}
\end{equation*}
$$

And applying the sets $\overline{1}: 1,2,3 ; \overline{2}: 4,2,3 ; \overline{3}: 4,3,1 ; \overline{4}: 4,1,2$, we can obtain the following
For $\overline{1}: 1,2,3$;

$$
\begin{equation*}
\frac{\partial B_{x}}{\partial x}+\frac{\partial B_{y}}{\partial y}+\frac{\partial B_{z}}{\partial z}=0 \tag{9}
\end{equation*}
$$

This equation can be written as

$$
\begin{equation*}
\nabla \cdot B=O \tag{10}
\end{equation*}
$$

For $\overline{2}: 4,2,3$;

$$
\begin{equation*}
\frac{\partial E_{z}}{\partial y}-\frac{\partial E_{y}}{\partial z}=-\frac{\partial B_{x}}{\partial t} \tag{11}
\end{equation*}
$$

For $\overline{3}: 4,3,1$;

$$
\begin{equation*}
\frac{\partial E_{x}}{\partial z}-\frac{\partial E_{z}}{\partial x}=-\frac{\partial B_{y}}{\partial t} \tag{12}
\end{equation*}
$$

For $\overline{4}$ : 4, 1,2;

$$
\begin{equation*}
\frac{\partial E_{y}}{\partial x}-\frac{\partial E_{x}}{\partial y}=-\frac{\partial B_{z}}{\partial t} \tag{13}
\end{equation*}
$$

Equations(11)-(13) are the $\mathrm{x}, \mathrm{y}, \mathrm{z}$ components respectively, multiplying them by appropriate unit vectors and adding we obtain;

$$
\begin{equation*}
\nabla \times E=-\frac{\partial B}{\partial t} \tag{14}
\end{equation*}
$$

In electrodynamics, Gauss law for electricity and Maxwell-Ampere's equation are gotten from:

$$
\begin{equation*}
\sum_{v=1}^{4} \frac{\partial F_{\mu v}}{\partial x^{v}}=\mu_{o} J_{\mu} ; \quad J_{\mu}=\left(J_{x}, J_{y}, J_{z}, i c \rho\right) \tag{15}
\end{equation*}
$$

According to Einstein summation convection; when the same letter index appears as subscript as well as superscript, then summation will appear over that index. Hence Eq(11) becomes:

$$
\begin{equation*}
\frac{\partial F_{\mu 1}}{\partial x^{1}}+\frac{\partial F_{\mu 2}}{\partial x^{2}}+\frac{\partial F_{\mu 3}}{\partial x^{3}}+\frac{\partial F_{\mu 4}}{\partial x^{4}}=\mu_{0} J_{\mu} ; \quad(\mu=1,2,3,4) \tag{16}
\end{equation*}
$$

For $\mu=1$;

$$
\begin{equation*}
\frac{\partial B_{z}}{\partial y}-\frac{\partial B_{y}}{\partial z}=\frac{1}{c^{2}} \frac{\partial E_{x}}{\partial t}+\mu_{o} J_{x} \tag{17}
\end{equation*}
$$

For $\mu=2$;

$$
\begin{equation*}
\frac{\partial B_{x}}{\partial z}-\frac{\partial B_{z}}{\partial y}=\frac{1}{c^{2}} \frac{\partial E_{y}}{\partial t}+\mu_{o} J_{y} \tag{18}
\end{equation*}
$$

For $\mu=3$;

$$
\begin{equation*}
\frac{\partial B_{y}}{\partial x}-\frac{\partial B_{x}}{\partial y}=\frac{1}{c^{2}} \frac{\partial E_{z}}{\partial t}+\mu_{o} J_{z} \tag{19}
\end{equation*}
$$

Equations (17)-(19) are the $\mathrm{x}, \mathrm{y}, \mathrm{z}$ components respectively, multiplying them by appropriate unit vectors and adding we obtain;

$$
\begin{equation*}
\nabla \times B=\frac{1}{c^{2}} \frac{\partial E}{\partial t}+\mu_{o} J \tag{20}
\end{equation*}
$$

For $\mu=4$;

$$
\begin{equation*}
\frac{\partial E_{x}}{\partial x}+\frac{\partial E_{y}}{\partial y}+\frac{\partial E_{z}}{\partial z}=c^{2} \mu_{0} \rho \tag{21}
\end{equation*}
$$

The last equation can be expressed as

$$
\begin{equation*}
\nabla . E=\frac{\rho}{\varepsilon_{o}} \tag{22}
\end{equation*}
$$

Where $c^{2}=\frac{1}{\varepsilon_{0} \mu_{0}}$
Equations (10),(14),(20),(22) are the familiar MFE's which describe the electric and magnetic fields arising from distributions of electric charges and currents, and how those fields change with time.
Hence the MFE's in frame $S$ may be expressed as:

$$
\left.\begin{array}{ll}
\nabla \cdot E=\frac{\rho}{\varepsilon_{o}} & ; \quad \nabla \times B=\frac{1}{c^{2}} \frac{\partial E}{\partial t}+\mu_{o} J  \tag{23}\\
\nabla \cdot B=0 & ; \quad \nabla \times E=-\frac{\partial B}{\partial t}
\end{array}\right\}
$$

By applying the relativistic principle to Eq.(23) they will preserve their form in frame $S^{\prime}$ and they are expressed as follows:

$$
\left.\begin{array}{ll}
\nabla^{\prime} . E^{\prime}=\frac{\rho^{\prime}}{\varepsilon_{o}} & ; \quad \nabla^{\prime} \times B^{\prime}=\frac{1}{c^{2}} \frac{\partial E^{\prime}}{\partial t^{\prime}}+\mu_{o} J^{\prime}  \tag{24}\\
\nabla^{\prime} . B^{\prime}=0 \quad ; \quad \nabla^{\prime} \times E^{\prime}=-\frac{\partial B^{\prime}}{\partial t^{\prime}}
\end{array}\right\}
$$

where $\rho, J, \rho^{\prime}, J^{\prime}$ are the relativistic charge and current density in frame $S$ and $S^{\prime}$ respectively. The light speed $c$ is defined in terms of pure electromagnetic constant as $c=\frac{1}{\sqrt{\varepsilon_{o} \mu_{o}}}$. But we know that $\varepsilon_{o}$ and $\mu_{o}$ have same value in all reference frames so $c^{\prime}=c$ which implies invariance of light speed.

## 3. DERIVING THE LORENTZ TRANSFORMATION

Taking the x-component of Eq.(23) and writing Eq.(4) in terms of cathesian component.

$$
\begin{align*}
& \frac{\partial B_{z}}{\partial y}-\frac{\partial B_{y}}{\partial z}=\frac{1}{c^{2}} \frac{\partial E_{x}}{\partial t}+\mu_{o} J_{x}  \tag{25}\\
& \frac{\partial E_{x}}{\partial x}+\frac{\partial E_{y}}{\partial y}+\frac{\partial E_{z}}{\partial z}=\frac{\rho}{\varepsilon_{o}} \tag{26}
\end{align*}
$$

Multiply Eq.(25) by $\gamma$ and Eq.(26) by $\frac{u \gamma}{c^{2}}$ and then subtracting we have:

$$
\begin{equation*}
\frac{\partial}{\partial y} \gamma\left(B_{z}-\frac{u}{c^{2}} E_{y}\right)-\frac{\partial}{\partial z} \gamma\left(B_{y}-\frac{u}{c^{2}} E_{z}\right)=\frac{\gamma}{c^{2}}\left(\frac{\partial}{\partial t}+u \frac{\partial}{\partial x}\right) E_{x}+\mu_{o} \gamma\left[J_{x}-u \rho\right] \tag{27}
\end{equation*}
$$

Taking the x-component of Eq.(24)

$$
\begin{equation*}
\frac{\partial B_{z}^{\prime}}{\partial y^{\prime}}-\frac{\partial B_{y}^{\prime}}{\partial z^{\prime}}=\frac{1}{c^{2}} \frac{\partial E_{x}^{\prime}}{\partial t^{\prime}}+\mu_{o} J_{x}^{\prime} \tag{28}
\end{equation*}
$$

Comparing Eq.(27) and Eq.(28)

$$
\begin{align*}
E_{x}^{\prime} & =E_{x} ; \quad B_{y}^{\prime}=\gamma\left(B_{y}-\frac{u}{c^{2}} E_{z}\right) ; \quad B_{z}^{\prime}=\gamma\left(B_{z}-\frac{u}{c^{2}} E_{y}\right) \\
\frac{\partial}{\partial t^{\prime}} & =\frac{\gamma}{c^{2}}\left(\frac{\partial}{\partial t}+u \frac{\partial}{\partial x}\right) ; \quad \frac{\partial}{\partial y^{\prime}}=\frac{\partial}{\partial y} ; \quad \frac{\partial}{\partial z^{\prime}}=\frac{\partial}{\partial z}  \tag{29}\\
J_{x}^{\prime} & =\gamma\left[J_{x}-u \rho\right]
\end{align*}
$$

Now multiply Eq.(25) by $u \gamma$ and Eq.(26) by $\gamma$ and then subtracting we have

$$
\begin{equation*}
\gamma\left(\frac{\partial}{\partial x}+\frac{u}{c^{2}} \frac{\partial}{\partial t}\right) E_{x}+\frac{\partial}{\partial y} \gamma\left(E_{y}-u B_{z}\right)+\frac{\partial}{\partial z} \gamma\left(E_{z}-u B_{y}\right)=\frac{\gamma}{\varepsilon_{o}}\left(\rho-\frac{u}{c^{2}} J_{x}\right) \tag{30}
\end{equation*}
$$

Taking the cathesian component of Eq.(24)

$$
\begin{equation*}
\frac{\partial E_{x}^{\prime}}{\partial x^{\prime}}+\frac{\partial E_{y}^{\prime}}{\partial y^{\prime}}+\frac{\partial E_{z}^{\prime}}{\partial z^{\prime}}=\frac{\rho^{\prime}}{\varepsilon_{o}} \tag{31}
\end{equation*}
$$

Comparing Eq.(30) with Eq.(31) and noting that $E_{x}^{\prime}=E_{x}$, we have:

$$
\begin{align*}
E_{y}^{\prime} & =\gamma\left(E_{y}-u B_{z}\right) ; \quad E_{z}^{\prime}=\gamma\left(E_{z}-u B_{y}\right) \\
\frac{\partial}{\partial x^{\prime}} & =\gamma\left(\frac{\partial}{\partial x}+\frac{u}{c^{2}} \frac{\partial}{\partial t}\right)  \tag{32}\\
\rho^{\prime} & =\gamma\left(\rho-\frac{u}{c^{2}} J_{x}\right)
\end{align*}
$$

The Eqs .(29),(32) are the differential Lorentz transformation. We can fix the scalar factor $\gamma$ by applying the relativistic principle (interchanging primed and the unprimed variables and letting $u=-u$.) on the z-part of Eq.(29).

$$
\begin{equation*}
B_{z}=\gamma\left(B_{z}^{\prime}+\frac{u}{c^{2}} E_{y}^{\prime}\right) \tag{33}
\end{equation*}
$$

Substituting the values of $B_{z}$ and $E_{y}$ from Eqs.(29),(32) we have:

$$
\begin{equation*}
B_{z}=\gamma\left[\gamma\left(B_{z}-\frac{u}{c^{2}} E_{y}\right)+\frac{u}{c^{2}} \gamma\left(E_{z}-u B_{y}\right)\right] \tag{34}
\end{equation*}
$$

$B_{z}=\gamma^{2}\left(1-\frac{u^{2}}{c^{2}}\right) B_{z}$
where

$$
\begin{equation*}
\gamma^{2}\left(1-\frac{u^{2}}{c^{2}}\right)=1 \text { or } \gamma=\frac{1}{\sqrt{1-\frac{u^{2}}{c^{2}}}} \tag{35}
\end{equation*}
$$

Starting now from the y-component of $\mathrm{Eq}(23)$ and applying Eq.(35) we have:

$$
\begin{equation*}
\frac{\partial B_{x}}{\partial z}-\gamma^{2}\left(1-\frac{u^{2}}{c^{2}}\right) \frac{\partial B_{z}}{\partial x}=\gamma^{2}\left(1-\frac{u^{2}}{c^{2}}\right) \frac{1}{c^{2}} \frac{\partial E_{y}}{\partial t}+\mu_{o} J_{y} \tag{36}
\end{equation*}
$$

Adding and subtracting $\frac{u}{c^{2}} \gamma^{2} \frac{\partial E_{y}}{\partial x}$ on the L.H.S and $\frac{u}{c^{2}} \gamma^{2} \frac{\partial B_{z}}{\partial t}$ on the R.H.S of Eq.(36) we have:

$$
\begin{equation*}
\frac{\partial B_{x}}{\partial z}-\gamma^{2}\left(\frac{\partial}{\partial x}+\frac{u}{c^{2}} \frac{\partial}{\partial t}\right)\left(B_{z}-\frac{u}{c^{2}} E_{y}\right)=\frac{\gamma^{2}}{c^{2}}\left(\frac{\partial}{\partial t}+u \frac{\partial}{\partial x}\right)\left(E_{y}-u B_{z}\right)+\mu_{o} J_{y} \tag{37}
\end{equation*}
$$

Taking the y-component of Eq.(24)

$$
\begin{equation*}
\frac{\partial B_{x}^{\prime}}{\partial z^{\prime}}-\frac{\partial B_{z}^{\prime}}{\partial x^{\prime}}=\frac{1}{c^{2}} \frac{\partial E_{y}^{\prime}}{\partial t^{\prime}}+\mu_{o} J_{y}^{\prime} \tag{38}
\end{equation*}
$$

Comparing Eq.(37) and Eq.(38)

$$
\begin{equation*}
B_{x}^{\prime}=B_{x} ; \quad J_{y}^{\prime}=J_{y} \tag{39}
\end{equation*}
$$

In a similar way starting from the z-component of $\mathrm{Eq}(23)$ we obtain:

$$
\begin{equation*}
J_{z}^{\prime}=J_{z} \tag{40}
\end{equation*}
$$

But the electromagnetic charge density $\rho$ for a particle of charge $q$ is $\rho=q \delta^{3}\left(x-x^{\prime}\right)$, and the definition of current density $J$ in frame $S$ is:

$$
\begin{equation*}
J=q v \delta^{3}\left(x-x^{\prime}\right)=\rho v \tag{41}
\end{equation*}
$$

By applying the relativistic principle the current density $J$ in frame $S^{\prime}$ is:

$$
\begin{equation*}
J^{\prime}=\rho^{\prime} v^{\prime} \tag{42}
\end{equation*}
$$

Applying Eqs.(41),(42) into Eqs(29),(32) we have

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$$
\begin{equation*}
v_{x}^{\prime}=\frac{v_{x}-u}{\gamma\left(1-\frac{u v_{x}}{c^{2}}\right)} \tag{43}
\end{equation*}
$$

Also from Eq.(39) and making use of Eq.(32) we have

$$
\begin{equation*}
v_{y}^{\prime}=\frac{v_{y}}{\gamma\left(1-\frac{u v_{x}}{c^{2}}\right)} \tag{44}
\end{equation*}
$$

Finally from Eq.(40) and making use of $\mathrm{Eq}(32)$ we have

$$
\begin{equation*}
v_{z}^{\prime}=\frac{v_{z}}{\gamma\left(1-\frac{u v_{x}}{c^{2}}\right)} \tag{45}
\end{equation*}
$$

The Eqs.(43)-(45) are the relativistic Lorentz velocity transformation.
Many researchers [12, 13, 16] have demonstrated the invariant of MFE's under LT, but have not used our approach. In our approach we begin with electromagnetic field tensors and obtain the MFE's in frames $S$ and $S^{\prime}$, we apply them using relativistic principle to obtain the differential LT and hence deduce the scalar factor $\gamma$. We also obtained the relativistic Lorentz velocity transformation and the results are consistent with [17]. Thus none of Einstein's results changes; it is only the approach that changes.

## 4. CONCLUSION

Our results show that there is no physical distinction between Lorentz force law (LFL) and MFE's, so MFE's should govern the relativistic electromagnetic phenomena exactly as LFL does. Here we extended the relativistic principle to hold true for MFE's as held by LFL and obtain the same results as [18, 19]. Here, we presented the LT in its differential form, deduced the scalar factor $\gamma$ and hence obtained the relativistic Lorentz velocity transformation equations.

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