

# A Fixed Point Theorem for Weakly C - Contraction Mappings of Integral Type.

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## ABSTRACT

In the present paper, we shall prove a fixed point theorem by using generalized weak C- contraction of integral type. Our result is generalization of very known results.

**Key words:** Metric space, fixed point, weak C- contraction.

**AMS Subject Classification:** 54H25

## 1 Introduction and Preliminaries

Let  $(X, d)$  be a complete metric space and  $T: X \rightarrow X$  a self-map of  $X$ . Suppose that  $F_f = \{x \in X \mid T(x) = x\}$  is the set of fixed points of  $f$ . The classical Banach's fixed point theorem is one of the pivotal results of functional analysis. by using the following contractive definition: there exists  $k \in [0, 1)$  such that  $\forall x, y \in X$ , we have

$$d(Tx, Ty) \leq kd(x, y) \quad (1.1)$$

If the metric space  $(X, d)$  is complete then the mapping satisfying (1.1) has a unique fixed point. Inequality (1.1) implies continuity of  $T$ . A natural question is that whether we can find contractive conditions which will imply existence of fixed point in a complete metric space but will not imply continuity.

Kannan [10,11] established the following result in which the above question has been answered in the affirmative.

If  $T: X \rightarrow X$  where  $(X, d)$  is complete metric space, satisfies the inequality

$$d(Tx, Ty) \leq k[d(x, Tx) + d(y, Ty)] \quad (1.2)$$

where  $0 < k < \frac{1}{2}$  and  $x, y \in X$ , then  $T$  has a unique fixed point.

The mapping  $T$  need not be continuous. The mapping satisfying (1.2) are called Kannan type mappings. There is a large literature dealing with Kannan type mappings and their generalization some of which are noted in [8], [17] and [19].

A similar contractive condition has been introduced by Chatterjee [6]. We call this contraction a C-contraction.

### Definition 1.1 C-contraction

Let  $T: X \rightarrow X$  where  $(X, d)$  is a metric space is called a C-contraction if there exists  $0 < k < \frac{1}{2}$  such that for all  $x, y \in X$  the following inequality holds:

$$d(Tx, Ty) \leq k[d(x, Ty) + d(y, Tx)] \quad (1.3)$$

**Theorem 1.1** A C-contraction defined on a complete metric space has a unique fixed point.

In establishing theorem 1.1 there is no requirement of continuity of the C-contraction.

It has been established in [15] that inequalities (1.1), (1.2) and (1.3) are independent of one another. C-contraction and its generalizations have been discussed in a number of works some of which are noted in [4], [8], [9] and [19].

Banach's contraction mapping theorem has been generalized in a number of recent papers. As for example, asymptotic contraction has been introduced by Kirk [12] and generalized Banach contraction conjecture has been proved in [1] and [14].

Particularly a weaker contraction has been introduced in Hilbert spaces in [2]. The following is the corresponding definition in metric space.

### Definition 1.2 Weakly contractive mapping

A mapping  $T: X \rightarrow X$  where  $(X, d)$  is complete metric space is said to be weakly contractive if  $d(Tx, Ty) \leq d(x, y) - \Psi(d(x, y))$ ,  $(1.4)$

Where  $x, y \in X$ ,  $\Psi: [0, \infty) \rightarrow [0, \infty)$  is continuous and non-decreasing,

$\Psi(x) = 0$  if and only if  $x = 0$  and  $\lim_{x \rightarrow \infty} \Psi(x) = \infty$ .

There are a number of works in which weakly contractive mappings have been considered. Some of these works are noted in [3],[7],[13], and [16].

In the present work in the same spirit we introduce a generalization of C- contraction.

**Definition1.3 Weak C- contraction:**

A mapping  $T : X \rightarrow X$ , where  $(X,d)$  is a metric space is said to be weakly C – contractive or a weak C-contraction if for all  $x, y \in X$ ,

$$d(Tx, Ty) \leq \frac{1}{2} [d(x,Ty) + d(y,Tx)] - \Psi(d(x,Ty), d(y,Tx)) \tag{1.5}$$

where  $\Psi: [0, \infty)^2 \rightarrow [0, \infty)$  is a continuous mapping such that  $\Psi(x,y) = 0$  if and only if  $x = y = 0$ .

If we take  $\Psi(x,y) = k(x+y)$  where  $0 < k < \frac{1}{2}$  then (1.5) reduces to (1.4), that is weak C – contractions are generalizations of C – contractions.

In a recent paper of Branciari [20] obtained a fixed point result for a single mapping satisfying an analogue of a Banach’s contraction principle for integral type inequality as below: there exists  $c \in [0,1)$  such that  $\forall x, y \in X$ , we have

$$\int_0^{d(Tx,Ty)} \varphi(t)dt \leq k \int_0^{d(x,y)} \varphi(t)dt$$

Where  $\varphi : R^+ \rightarrow R^+$  is a Lebesgue – integrable mapping which is summable, non-negative and such that for each  $\epsilon > 0, \int_0^\epsilon \varphi(t)dt > 0$ .

Our main result is extended and modified to the weak C – contraction mapping in integral type .

**MAIN RESULT**

Let  $T : X \rightarrow X$  where  $(X,d)$  is complete metric space be a weak C-contraction, which is satisfying the following property:

$$\int_0^{d(Tx,Ty)} \varphi(t)dt \leq \alpha \int_0^{d(x,Ty)+d(y,Tx)} \varphi(t)dt + \beta \int_0^{\max\{d(x,Tx),d(y,Ty)\}} \varphi(t)dt - \int_0^{\Psi\{d(x,Ty),d(y,Tx),d(x,Tx),d(y,Ty)\}} \varphi(t)dt \tag{2.1}$$

Then T has a unique fixed point.

Where  $\alpha, \beta \in [0,1)$  with  $2\alpha + \beta \leq 1$  and  $\varphi : R^+ \rightarrow R^+$  is a Lebesgue – integrable mapping which is summable,non negative and such that for each  $\epsilon > 0, \int_0^\epsilon \varphi(t)dt > 0$  and  $\Psi: [0, \infty)^2 \rightarrow [0, \infty)$  is a continuous mapping such that  $\Psi(x,y) = 0$  if and only if  $x = y = 0$ .

**Proof :** Let  $x_0 \in X$  and for all  $n \geq 1, x_{n+1} = Tx_n$ .

If  $x_{n+1} = x_n = Tx_n$ . Then  $x_n$  is a fixed point of T.

So we assume,  $x_{n+1} \neq x_n$ .

Putting  $x = x_{n-1}$  and  $y = x_n$  in (2.1) we have for all  $n = 0,1,2, \dots$

$$\begin{aligned} \int_0^{d(x_n,x_{n+1})} \varphi(t)dt &= \int_0^{d(Tx_{n-1},Tx_n)} \varphi(t)dt \\ &\leq \alpha \int_0^{d(x_{n-1},Tx_n)+d(x_n,Tx_{n-1})} \varphi(t)dt \\ &+ \beta \int_0^{\max\{d(x_{n-1},Tx_{n-1}),d(x_n,Tx_n)\}} \varphi(t)dt \\ &- \int_0^{\Psi\{d(x_{n-1},Tx_n),d(x_n,Tx_{n-1}),d(x_{n-1},Tx_{n-1}),d(x_n,Tx_n)\}} \varphi(t)dt \\ &= \alpha \int_0^{d(x_{n-1},x_{n+1})+d(x_n,x_n)} \varphi(t)dt \\ &+ \beta \int_0^{\max\{d(x_{n-1},x_n),d(x_n,x_{n+1})\}} \varphi(t)dt \\ &- \int_0^{\Psi\{d(x_{n-1},x_{n+1}),d(x_n,x_n),d(x_{n-1},x_n),d(x_n,x_{n+1})\}} \varphi(t)dt \end{aligned}$$

Since T is Weakly C – contraction, this gives that

$$\Psi\{d(x_{n-1},x_{n+1}),0,d(x_{n-1},x_n),d(x_n,x_{n+1})\} = 0 \text{ and}$$

$$\int_0^{d(x_n,x_{n+1})} \varphi(t)dt \leq \alpha \int_0^{d(x_{n-1},x_{n+1})} \varphi(t)dt + \beta \int_0^{\max\{d(x_{n-1},x_n),d(x_n,x_{n+1})\}} \varphi(t)dt \tag{2.2}$$

Now here arise two cases:

**Case I:** - If we choose

$$\max\{d(x_{n-1},x_n),d(x_n,x_{n+1})\} = d(x_{n-1},x_n)$$

Then (2.2) can be written as

$$\int_0^{d(x_n,x_{n+1})} \varphi(t)dt \leq \alpha \int_0^{d(x_{n-1},x_n)} \varphi(t)dt + \alpha \int_0^{d(x_n,x_{n+1})} \varphi(t)dt + \beta \int_0^{d(x_{n-1},x_n)} \varphi(t)dt$$

$$(1-\alpha) \int_0^{d(x_n, x_{n+1})} \varphi(t) dt = (\alpha + \beta) \int_0^{d(x_{n-1}, x_n)} \varphi(t) dt$$

$$\int_0^{d(x_n, x_{n+1})} \varphi(t) dt = \frac{\alpha + \beta}{1 - \alpha} \int_0^{d(x_{n-1}, x_n)} \varphi(t) dt$$

$$\int_0^{d(x_n, x_{n+1})} \varphi(t) dt \leq k \int_0^{d(x_{n-1}, x_n)} \varphi(t) dt \text{ where } k = \frac{\alpha + \beta}{1 - \alpha} \leq 1$$

**Case 2 :** - If we choose

$$\max \{ d(x_{n-1}, x_n), d(x_n, x_{n+1}) \} = d(x_n, x_{n+1})$$

Then (2.2) can be written as

$$\int_0^{d(x_n, x_{n+1})} \varphi(t) dt \leq \alpha \int_0^{d(x_{n-1}, x_n)} \varphi(t) dt + \alpha \int_0^{d(x_n, x_{n+1})} \varphi(t) dt$$

$$+ \beta \int_0^{d(x_n, x_{n+1})} \varphi(t) dt$$

$$[1 - (\alpha + \beta)] \int_0^{d(x_n, x_{n+1})} \varphi(t) dt = \alpha \int_0^{d(x_{n-1}, x_n)} \varphi(t) dt$$

$$\int_0^{d(x_n, x_{n+1})} \varphi(t) dt = \frac{\alpha}{1 - (\alpha + \beta)} \int_0^{d(x_{n-1}, x_n)} \varphi(t) dt$$

$$\int_0^{d(x_n, x_{n+1})} \varphi(t) dt \leq k \int_0^{d(x_{n-1}, x_n)} \varphi(t) dt, \text{ where } k = \frac{\alpha}{1 - (\alpha + \beta)} \leq 1 \quad (2.3)$$

From above both cases:

$$\int_0^{d(x_n, x_{n+1})} \varphi(t) dt \leq k^2 \int_0^{d(x_{n-2}, x_{n-1})} \varphi(t) dt$$

$$\leq k^3 \int_0^{d(x_{n-3}, x_{n-2})} \varphi(t) dt$$

$$\leq \dots$$

$$\leq k^n \int_0^{d(x_0, x_1)} \varphi(t) dt$$

Taking limit as  $n \rightarrow \infty$ , we get

$$\lim_{n \rightarrow \infty} \int_0^{d(x_n, x_{n+1})} \varphi(t) dt = 0, \text{ as } k \in [0, 1) \quad (2.4)$$

Now we prove that  $\{x_n\}$  is a Cauchy sequence. Suppose it is not. Then there exists an  $\varepsilon > 0$  and sub sequence  $\{y_{m(p)}\}$  and  $\{y_{n(p)}\}$  such that

$$m(p) < n(p) < m(p+1) \text{ with}$$

$$d(x_{n(p)}, x_{m(p)}) \geq \varepsilon, d(x_{n(p)-1}, x_{m(p)}) < \varepsilon \quad (2.5)$$

Now

$$d(x_{m(p)-1}, x_{n(p)-1}) \leq d(x_{m(p)-1}, x_{m(p)}) + d(x_{m(p)}, x_{n(p)-1})$$

$$< d(x_{m(p)-1}, x_{m(p)}) + \varepsilon \quad (2.6)$$

From (2.4), (2.6), we get

$$\lim_{p \rightarrow \infty} \int_0^{d(x_{m(p)-1}, x_{n(p)-1})} \varphi(t) dt \leq \int_0^\varepsilon \varphi(t) dt \quad (2.7)$$

Using (2.3), (2.5), and (2.7) we get,

$$\int_0^\varepsilon \varphi(t) dt \leq \int_0^{d(x_{n(p)}, x_{m(p)})} \varphi(t) dt$$

$$\leq k \int_0^{d(x_{n(p)-1}, x_{m(p)-1})} \varphi(t) dt$$

$$\leq k \int_0^\varepsilon \varphi(t) dt$$

Which is contradiction, since  $k \in (0, 1)$ . therefore  $\{x_n\}$  is a Cauchy sequence. Since  $(X, d)$  is complete metric space, therefore we call the limit  $z$ .

From (2.1), we get

$$\int_0^{d(Tz, x_{n+1})} \varphi(t) dt = \int_0^{d(Tz, Tx_n)} \varphi(t) dt$$

$$\leq \alpha \int_0^{d(z, Tx_n) + d(x_n, Tz)} \varphi(t) dt$$

$$+ \beta \int_0^{\max \{ d(z, Tz), d(x_n, Tx_n) \}} \varphi(t) dt$$

$$- \int_0^{\Psi \{ d(z, Tx_n), d(x_n, Tz), d(z, Tz), d(x_n, Tx_n) \}} \varphi(t) dt$$

Taking limit as  $n \rightarrow \infty$ , we get

$$\int_0^{d(Tz, z)} \varphi(t) dt \leq \alpha \int_0^{d(z, Tz)} \varphi(t) dt + \beta \int_0^{d(z, Tz)} \varphi(t) dt$$

$$= (\alpha + \beta) \int_0^{d(z, Tz)} \varphi(t) dt$$

Which is Contradiction

Therefore  $Tz = z$

That is  $z$  is a fixed point of  $T$  in  $X$ .

**Uniqueness** : Let  $w$  is another fixed point of  $T$  in  $X$  such that  $z \neq w$ , then we have

From (2.1), we get

$$\begin{aligned} \int_0^{d(z,w)} \varphi(t) dt &= \int_0^{d(Tz,Tw)} \varphi(t) dt \\ &\leq \alpha \int_0^{d(z,Tw)+d(w,Tz)} \varphi(t) dt + \beta \int_0^{\max\{d(z,Tz),d(w,Tw)\}} \varphi(t) dt \\ &\quad - \int_0^{\Psi\{d(z,Tw),d(w,Tz),d(z,Tz),d(w,Tw)\}} \varphi(t) dt \\ \int_0^{d(z,w)} \varphi(t) dt &\leq 2\alpha \int_0^{d(z,w)} \varphi(t) dt \end{aligned}$$

Which is contradiction

So  $z = w$  that is,  $z$  is unique fixed point of  $T$  in  $X$ .

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