A Common Fixed Point Theorem for Six Mappings in G-Banach Space with Weak-Compatibility

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ABSTRACT

The aim of this paper is to introduce the concept of G-Banach Space and prove a common fixed point theorem for six mappings in G-Banach spaces with weak-compatibility.

Keywords: Fixed point , common fixed point , G-Banach Space , Continuous mappings , weak compatible mappings.

Introduction : This is well know that the fundamental contraction principle for proving fixed points results is the Banach Contraction principle. There have been a number of generalization of metric space and Banach space. One such generalization is G-Banach space. The concept of G-Banach space is introduce by Shrivastava R,Animesh,Yadav R.N.[4] which is a probable modification of the ordinary Banach Space.

Recently in 2012, R.K. Bharadwaj [2] introduced fixed point theorems in G-Banach Space through weak compatibility and gave the following fixed point theorems for four mappings-

Theorems[A]: Let X be a G-Banach Space, such that ∇ Satisfy property with $\alpha - \alpha \le 1$. If A, B, S and T be mapping from X into itself satisfying the following condition:

- I. $A(X) \subseteq T(X)$, $B(X) \subseteq S(X)$ and T(X) or S(X) is a closed subset of X.
- II. The Pair (A,S) and (B,T) are weakly compatible,
- III. For all $x, y \in X$

$$\begin{split} \|\operatorname{Ax} - \operatorname{By}\|_{g} &\leq k_{1} \left(\frac{\|\operatorname{Sx} - \operatorname{Ax}\|_{g} \|\operatorname{Sx} - \operatorname{By}\|_{g}}{\|\operatorname{Sx} - \operatorname{Ty}\|_{g}} \nabla \frac{\|\operatorname{Tx} - \operatorname{Ax}\|_{g} \|\operatorname{Ty} - \operatorname{By}\|_{g}}{\|\operatorname{Sx} - \operatorname{Ty}\|_{g}} \right) \\ &+ k_{2} \max \left(\frac{\|\operatorname{Sx} - \operatorname{Ax}\|_{g} \|\operatorname{Ty} - \operatorname{By}\|_{g}}{\|\operatorname{Sx} - \operatorname{Ty}\|_{g}} \nabla \frac{\|\operatorname{Sx} - \operatorname{By}\|_{g} \|\operatorname{Ty} - \operatorname{Ax}\|_{g}}{\|\operatorname{Sx} - \operatorname{Ty}\|_{g}} \right) \\ &+ k_{3} \left(\|\operatorname{Sx} - \operatorname{Ax}\|_{g} \nabla \|\operatorname{Ty} - \operatorname{By}\|_{g} \nabla \|\operatorname{Sx} - \operatorname{By}\|_{g} \nabla \|\operatorname{Ty} - \operatorname{Ax}\|_{g} \nabla \|\operatorname{Sx} - \operatorname{Ty}\|_{g} \right) \\ &+ k_{3} \left(\|\operatorname{Sx} - \operatorname{Ax}\|_{g} \nabla \|\operatorname{Ty} - \operatorname{By}\|_{g} \nabla \|\operatorname{Sx} - \operatorname{By}\|_{g} \nabla \|\operatorname{Ty} - \operatorname{Ax}\|_{g} \nabla \|\operatorname{Sx} - \operatorname{Ty}\|_{g} \right) \end{split}$$

Where $k_1,k_2,k_3 \! > \! 0 \,$ and $\, 0 < k_1 + \, k_2 + k_3 < \! 1.$ Then A , B , S and T have a unique common fixed point in X.

In 1980, Singh and Singh[5] gave the following theorem on metric space for self maps which is use to our main result-

Theorems[**B**]: Let P, Q and T be self maps of a metric space (X, d) such that

(i) PT = TP and QT = TQ, (ii) $P(X) \cup Q(X) \subseteq T(X)$, (iii) T is continuous,

(iv)
$$d(Px, Qy) \le c \lambda (x, y),$$

where
$$\lambda(x, y) = \max\{d(Tx, Ty), d(Px, Tx), d(Qy, Ty), \frac{1}{2}[d(Px, Ty)+d(Qy, Ty)]\}$$

for all $x, y \in X$ and $0 \le < 1$. Further if

(v) X is complete then P, Q, T have a unique common fixed point in X.

Just we recall the some definition of G-Banach space for the sake of completeness which as follows-

N be the set of natural numbers and R⁺ be the set of all positive numbers let binary operation ∇ : R⁺ × R⁺ → R⁺ satisfies the following conditions:

- i. ∇ is associative and commutative,
- ii. ∇ is continuous.

Five typical example are as follows:

i. $a \nabla b = max (a,b)$

ii. $a \nabla b = a+b$

- iii. $a \nabla b = a.b$
- iv. $a \nabla b = a.b+a+b$

v.
$$a \nabla b = \frac{ab}{\max(a,b,1)}$$

The binary operation ∇ is said to satisfy α -property if there exists a positive real number α , **Definition 1:** such that a ∇ b $\leq \alpha$ max (a,b) for every a,b $\in \mathbb{R}^+$

Example: If we define a ∇ b = a + b for each a, b $\in \mathbb{R}^+$ then for $\alpha \ge 2$, we have

a
$$\nabla$$
 b $\leq \alpha \max(a,b)$

if we define a ∇ b = $\frac{ab}{\max(a,b,1)}$ for each a,b $\in \mathbb{R}^+$ then for $\alpha \ge 1$, we have

a ∇ b $\leq \alpha \max(a,b)$

Definition 2: Let x be a nonempty set ,A Generalized Normed Space on X is a function $\| \|_g : x \times x \to R^+$ that satisfies the following conditions for each x,y,z, C X

1.
$$\| \mathbf{x} - \mathbf{y} \|_{g} > 0$$

1. $\begin{aligned} x-y &\|_{g} \neq 0 \\ x-y &\|_{g} = 0 \text{ if and only if } x = y \\ x-y &\|_{g} = \|y-x\|_{g} \\ 4. &\|x\|_{g} = \|\alpha\| \|x\|_{g} \text{ for any scalar } \alpha \\ 5. &\|x-y\|_{g} \leq \|x-z\|_{g} \nabla \|z-x\|_{g} \\ The pair (x, \|\|\|_{g}) \text{ is called generalized Normed Space or simply G-Normed Space.} \\ Definition 3: A Sequence in X is said converges to x if <math>\|x_{n}-x\|_{g} \to 0$, as $n \to \infty$. That is for each $\epsilon > 0$ there exists $n_{0} \in N$ such that for every $n \geq n_{0}$ implies that $\|x_{n}-x\|_{g} < \epsilon \\ Definition 4: A sequence (x) is said to be Cauchy sequence if for every <math>n \geq 0 \\ x = 0 \\$

Definition 4: A sequence $\{x_n\}$ is said to be Cauchy sequence if for every $\epsilon > 0$ there exists $n_0 \epsilon N$ such that $\|\mathbf{x}_{m} \cdot \mathbf{x}_{n}\|_{g} < \epsilon$ for each $m, n \ge n_{0}$. G-Normed Space is said to be G-Banach Space if for every Cauchy sequence is converges in it.

Let $(x, \| \|_{g})$ be a G-Normed Space for r>0 we define **Definition 5:**

$$\mathbf{B}_{g}(\mathbf{x},\mathbf{r}) = \{\mathbf{y} \in \mathbf{X} : \|\mathbf{x} \cdot \mathbf{y}\|_{g} < \mathbf{r} \}$$

Let X be a G-normed Space and A be a subset of X, then for every x \in A, there exists r > 0 such that B_g(x,r) \subseteq A, then the subset A is called open subset of X. A subset A of X is said to be closed if the complement of A is open in X.

Let A and S be mappings from a G-Banach space X into itselt. Then the mappings are said to **Definition 6:** be weakly compatible if they are commute at there coincidence point that is Ax = Sx implies that ASx = SAx

Here we generalized and extend the results of R.K.Bhardwaj[2] (theorem A) for six mappings opposed to four mappings in G-Banach space using the concept of weak-compatibility.

Main Result :

THEOREM(1): Let X be a G-Banach Space, such that ∇ Satisfy property with $\alpha - \alpha \le 1$. If P, Q, A, B, S and T be mapping from X into itself satisfying the following condition:

- $A(X) \subseteq Q(X) \cup T(X)$, $B(X) \subseteq P(X) \cup S(X)$ and T(X) or S(X) is a closed subset of X. I.
- The Pair (A,S) and (P,S), (B,T) and (Q,T) are weakly compatible, II.
- III. For all $x, y \in X$

$$\|A\mathbf{x} - B\mathbf{y}\|_{g} \leq$$

$$\leq \alpha \max \begin{pmatrix} \|Sx - By\|_{g} \|Ty - Ax\|_{g} \nabla \frac{\|Px - Ax\|_{g} \|Qy - By\|_{g}}{\|Sx - Py\|_{g}} \nabla \frac{\|Sx - Ty\|_{g} \|Qy - By\|_{g}}{\|Qy - Ax\|_{g} + \|Px - Ax\|_{g}} \nabla \\ \left\{ \frac{\|Px - Qx\|_{g} + \|Bx - Ty\|_{g}}{\|Px - By\|_{g}} \right\} \|Sx - By\|_{g} \\ + \beta \max \begin{pmatrix} \|Sx - Ty\|_{g} \nabla \|Px - Sx\|_{g} \nabla \|Qy - By\|_{g} \nabla \|Px - Ty\|_{g} \nabla \|Qy - Sx\|_{g} \nabla \\ \frac{\|Px - Ax\|_{g} \|Qy - By\|_{g}}{\|Px - Qy\|_{g}} \nabla \frac{\|Sx - Ty\|_{g} \|Qy - Sx\|_{g}}{\|Px - Qy\|_{g}} \end{pmatrix}$$

Where α , $\beta > 0$ and $0 < \alpha + \beta < 1$. Then P, Q, A, B, S and T have a unique common fixed point in X.

Proof: Let x_0 be an arbitrary point in X then by (i) we choose a point x_1 in X such that $y_0 = Ax_0 =$ $Tx_1 = Qx_1$ and $y_1 = Bx_1 = Sx_2 = Px_2$.

In general there exists a sequence $\{y_n\}$ such that we claim that the sequence $\{y_n\}$ is a Cauchy sequence. By (iii) we have $\| \mathbf{y}_{2n} - \mathbf{y}_{2n+1} \|_{g} = \| \mathbf{A} \mathbf{x}_{2n} - \mathbf{B} \mathbf{x}_{2n+1} \|_{g}$ $\leq \alpha \max\left(\begin{aligned} & \left\| Sx_{2n} - Bx_{2n+1} \right\|_{g} \|Tx_{2n+1} - Ax_{2n} \|_{g} \nabla \frac{\|Px_{2n} - Ax_{2n} \|_{g} \|Qx_{2n+1} - Bx_{2n+1} \|_{g}}{\|Sx_{2n} - Px_{2n+1} \|_{g}} \nabla \left\{ \frac{\|Sx_{2n} - Tx_{2n+1} \|_{g} \|Qx_{2n+1} - Bx_{2n+1} \|_{g}}{\|Qx_{2n+1} - Ax_{2n} \|_{g} + \|Px_{2n} - Ax_{2n} \|_{g}} \nabla \left\{ \frac{\|Px_{2n} - Qx_{2n} \|_{g} + \|Bx_{2n} - Tx_{2n+1} \|_{g}}{\|Px_{2n} - Bx_{2n+1} \|_{g}} \right\} \|Sx_{2n} - Bx_{2n+1} \|_{g}} \end{aligned} \right)$ $\|Sx_{2n} - Tx_{2n+1}\|_{g} \nabla \|Px_{2n} - Sx_{2n}\|_{g} \nabla \|Qx_{2n+1} - Bx_{2n+1}\|_{g} \nabla \|Px_{2n} - Tx_{2n+1}\|_{g} \nabla \|Qx_{2n+1} - Sx_{2n}\|_{g} \nabla \|Qx_{2n} - Sx_{2n}\|_{g} \nabla \|Q$ $+\beta \max \left\{ \frac{\|Px_{2n} - Ax_{2n}\|_{g} \|Qx_{2n+1} - Bx_{2n+1}\|_{g}}{\|Px_{2n} - Qx_{2n+1}\|_{g}} \nabla \frac{\|Sx_{2n} - Tx_{2n+1}\|_{g} \|Qx_{2n+1} - Sx_{2n}\|_{g}}{\|Px_{2n} - Qx_{2n+1}\|_{g}} \right\}$ $\leq \alpha \max \begin{pmatrix} \|y_{2n-1} - y_{2n-1}\|_{g} \|y_{2n} - y_{2n}\|_{g} \nabla \frac{\|y_{2n-1} - y_{2n}\|_{g} \|y_{2n} - y_{2n+1}\|_{g}}{\|y_{2n-1} - y_{2n}\|_{g}} \nabla \\ \frac{\|y_{2n-1} - y_{2n}\|_{g} \|y_{2n} - y_{2n+1}\|_{g}}{\|y_{2n} - y_{2n}\|_{g} + \|y_{2n-1} - y_{2n}\|_{g}} \nabla \left\{ \frac{\|y_{2n-1} - y_{2n-1}\|_{g} + \|y_{2n} - y_{2n+1}\|_{g}}{\|y_{2n-1} - y_{2n}\|_{g}} \right\} \|y_{2n-1} - y_{2n}\|_{g} \end{pmatrix}$ $+\beta \max \left\{ \frac{\|y_{2n-1} - y_{2n}\|_{g} \nabla \|y_{2n-1} - y_{2n-1}\|_{g} \nabla \|y_{2n} - y_{2n+1}\|_{g} \nabla \|y_{2n-1} - y_{2n}\|_{g} \nabla \|y_{2n} - y_{2n-1}\|_{g} \nabla \|y_{2n} - y_{2n-1}\|_{g} \nabla \|y_{2n-1} - y_{2n}\|_{g} \nabla \|y_{2n} - y_{2n-1}\|_{g} \nabla \|y_{2n} - y_{2n}\|_{g} \nabla \|y_{2n} - y_{2n-1}\|_{g} \nabla \|y_{2n} - y_{2n}\|_{g} \nabla \|y_{2n} - y_{2n}\|_$ $\|y_{2n} - y_{2n+1}\|_{g} \leq (\alpha + \beta) \|y_{2n-1} - y_{2n}\|_{g}$ That is by induction we can show that $\| y_{2n} - y_{2n+1} \|_{g} \le (\alpha + \beta)^{n} \| y_{0} - y_{1} \|_{g} \| y_{2n} - y_{2n+1} \|_{g}$ As $n \to \infty || y_{2n} - y_{2n+1} ||_g \to 0$, for any integer $m \ge n$ It follows that the sequence $\{y_n\}$ is a Cauchy sequence which converges to $\ y\in X$. This implies that $\ \lim n\to\infty \ y_n\ =\ \lim n\to\infty \ Ax_{2n}\ =\ \lim n\to\infty \ Tx_{2n+1}\ =\ \lim n\to\infty \ Qx_{2n+1}\ =\ \lim n\to\infty$ $Bx_{2n+1} = \lim n \to \infty Sx_{2n+2} = \lim n \to \infty Px_{2n+2} = y$ Now let us assume that T(X) is closed subset of X, then there exists $v \in X$ such that

$$Tv = Qv = y$$

We now prove that Bv = y, By (iii) we get

$$\begin{split} \|Ax_{2n} - Bv\|_{g} &\leq \alpha \max \begin{pmatrix} \|Sx_{2n} - Bv\|_{g} \|Tv - Ax_{2n}\|_{g} \nabla \frac{\|Px_{2n} - Ax_{2n}\|_{g} \|Qv - Bv\|_{g}}{\|Sx_{2n} - Pv\|_{g}} \nabla \\ &\frac{\|Sx_{2n} - Tv\|_{g} \|Qv - Bv\|_{g}}{\|Qv - Ax_{2n}\|_{g} + \|Px_{2n} - Ax_{2n}\|_{g}} \nabla \begin{cases} \frac{\|Px_{2n} - Qx_{2n}\|_{g} + \|Bx_{2n} - Tv\|_{g}}{\|Px_{2n} - Bv\|_{g}} \\ &\frac{\|Sx_{2n} - Tv\|_{g} \nabla \|Px_{2n} - Ax_{2n}\|_{g}}{\|Qv - Bv\|_{g}} \nabla \|Qv - Bv\|_{g} \nabla \|Px_{2n} - Bv\|_{g}} \\ &+ \beta \max \begin{pmatrix} \|Sx_{2n} - Tv\|_{g} \nabla \|Px_{2n} - Sx_{2n}\|_{g} \nabla \|Qv - Bv\|_{g} \nabla \|Px_{2n} - Tv\|_{g} \nabla \|Qv - Sx_{2n}\|_{g} \nabla \\ &\frac{\|Px_{2n} - Ax_{2n}\|_{g} \|Qv - Bv\|_{g}}{\|Px_{2n} - Qv\|_{g}} \nabla \frac{\|Sx_{2n} - Tv\|_{g} \|Qv - Sx_{2n}\|_{g}}{\|Px_{2n} - Qv\|_{g}} \end{pmatrix} \\ &\|y - Bv\|_{g} \leq (\alpha + \beta) \|y - Bv\|_{g} \end{split}$$

Which is contradiction, it follows that Bv = y = Tv = Qv. Since (B,T) and (Q,T) are weakly compatible mappings, then we have

BTv = TBv and QTv = TQv By = Ty and Qy = TyWhich implies By = Qy.

Now we prove that By = y for this by using (iii) we get

 $\|Ax_{2n} - By\|_{g}$

$$\leq \alpha \max \begin{pmatrix} \|Sx_{2n} - By\|_{g} \|Ty - Ax_{2n}\|_{g} \nabla \frac{\|Px_{2n} - Ax_{2n}\|_{g} \|Qy - By\|_{g}}{\|Sx_{2n} - Py\|_{g}} \nabla \\ \frac{\|Sx_{2n} - Ty\|_{g} \|Qy - By\|_{g}}{\|Qy - Ax_{2n}\|_{g} + \|Px_{2n} - Ax_{2n}\|_{g}} \nabla \left\{ \frac{\|Px_{2n} - Qx_{2n}\|_{g} + \|Bx_{2n} - Ty\|_{g}}{\|Px_{2n} - By\|_{g}} \right\} \|Sx_{2n} - By\|_{g} \end{pmatrix} \\ + \beta \max \begin{pmatrix} \|Sx_{2n} - Ty\|_{g} \nabla \|Px_{2n} - Sx_{2n}\|_{g} \nabla \|Qy - By\|_{g} \nabla \|Px_{2n} - Ty\|_{g} \nabla \|Qy - Sx_{2n}\|_{g} \nabla \\ \frac{\|Px_{2n} - Ax_{2n}\|_{g} \|Qy - By\|_{g}}{\|Px_{2n} - Qy\|_{g}} \nabla \frac{\|Sx_{2n} - Ty\|_{g} \|Qy - Sx_{2n}\|_{g}}{\|Px_{2n} - Qy\|_{g}} \end{pmatrix} \\ \|Ax_{2n} - By\|_{g} \leq (\alpha + \beta) \|y - By\|_{g} \end{cases}$$

Which is contradiction. Thus By = y = Ty = Qy -----(A) Since

 $B(X) \subseteq P(X) \cup S(X)$, there exists $w \in X$. such that sw = y = Pw . we show that Aw = y From (iii) we have

 $\|\mathbf{A}\mathbf{w} - \mathbf{B}\mathbf{y}\|_{g}$

$$\leq \alpha \max \begin{pmatrix} \|\operatorname{Sw} - \operatorname{By}\|_{g} \|\operatorname{Ty} - \operatorname{Aw}\|_{g} \nabla \frac{\|\operatorname{Pw} - \operatorname{Aw}\|_{g} \|\operatorname{Qy} - \operatorname{By}\|_{g}}{\|\operatorname{Sw} - \operatorname{Py}\|_{g}} \nabla \\ \frac{\|\operatorname{Sw} - \operatorname{Ty}\|_{g} \|\operatorname{Qy} - \operatorname{By}\|_{g}}{\|\operatorname{Qy} - \operatorname{Aw}\|_{g} + \|\operatorname{Pw} - \operatorname{Aw}\|_{g}} \nabla \left\{ \frac{\|\operatorname{Pw} - \operatorname{Qw}\|_{g} + \|\operatorname{Bw} - \operatorname{Ty}\|_{g}}{\|\operatorname{Pw} - \operatorname{By}\|_{g}} \right\} \|\operatorname{Sw} - \operatorname{By}\|_{g}} \end{pmatrix} \\ + \beta \max \begin{pmatrix} \|\operatorname{Sw} - \operatorname{Ty}\|_{g} \nabla \|\operatorname{Pw} - \operatorname{Sw}\|_{g} \nabla \|\operatorname{Qy} - \operatorname{By}\|_{g} \nabla \|\operatorname{Pw} - \operatorname{Ty}\|_{g} \nabla \|\operatorname{Qy} - \operatorname{Sw}\|_{g} \nabla \\ \frac{\|\operatorname{Pw} - \operatorname{Aw}\|_{g} \|\operatorname{Qy} - \operatorname{By}\|_{g}}{\|\operatorname{Pw} - \operatorname{Qy}\|_{g}} \nabla \frac{\|\operatorname{Sw} - \operatorname{Ty}\|_{g} \|\operatorname{Qy} - \operatorname{Sw}\|_{g}}{\|\operatorname{Pw} - \operatorname{Qy}\|_{g}} \end{pmatrix} \end{pmatrix}$$

 $\|Aw - y\|_{g} \leq (\alpha + \beta) \|Aw - y\|_{g}$ Which is contradiction, so that Aw = y = Sw = Pw. Since (A, S) and (P, S) are weakly compatible, then ASw = Saw and PSw = SPwAy = Sy Py = Sy

Therefore Ay = Py

Now we Show that Ay = y, From (iii) we have

$$\|Ay - By\|_{g} \le \alpha \max \begin{pmatrix} \|Sy - By\|_{g} \|Ty - Ay\|_{g} \nabla \frac{\|Py - Ay\|_{g} \|Qy - By\|_{g}}{\|Sy - Py\|_{g}} \nabla \\ \frac{\|Sy - Ty\|_{g} \|Qy - By\|_{g}}{\|Qy - Ay\|_{g} + \|Py - Ay\|_{g}} \nabla \left\{ \frac{\|Py - Qy\|_{g} + \|By - Ty\|_{g}}{\|Py - By\|_{g}} \right\} \|Sy - By\|_{g} \end{pmatrix}$$

$$+ \beta \max \left(\frac{\| Sy - Ty \|_{g} \nabla \| Py - Sy \|_{g} \nabla \| Qy - By \|_{g} \nabla \| Py - Ty \|_{g} \nabla \| Qy - Sy \|_{g} \nabla}{\| Py - Ay \|_{g} \| Qy - By \|_{g}} \nabla \frac{\| Sy - Ty \|_{g} \| Qy - Sy \|_{g}}{\| Py - Qy \|_{g}} \right)$$

 $\|\operatorname{Ay} - y\|_{g} \le (\alpha + \beta) \|\operatorname{Ay} - y\|_{g}$

Which is contradiction thus Ay = y and therefore

Ay = Sy = Py = y -----(B)

Now from equation (A) and (B) we get

Ay = By = Py = Qy = Sy = Ty = y.

Hence $\, y \,$ is a common fixed $\, point \, of \, A \, , B \, , \, S \, , \, T \, , \, P \, and \, Q$.

Uniqueness:

Let us assume that x is another fixed point of A, B, S, T, P and Q different from y in X. Then from (iii) we have

$$\begin{split} \|\operatorname{Ax} - \operatorname{By}\|_{g} &\leq \\ &\leq \alpha \max \begin{pmatrix} \|\operatorname{Sx} - \operatorname{By}\|_{g} \|\operatorname{Ty} - \operatorname{Ax}\|_{g} \nabla \frac{\|\operatorname{Px} - \operatorname{Ax}\|_{g} \|\operatorname{Qy} - \operatorname{By}\|_{g}}{\|\operatorname{Sx} - \operatorname{Py}\|_{g}} \nabla \frac{\|\operatorname{Sx} - \operatorname{Ty}\|_{g} \|\operatorname{Qy} - \operatorname{By}\|_{g}}{\|\operatorname{Qy} - \operatorname{Ax}\|_{g} + \|\operatorname{Px} - \operatorname{Ax}\|_{g}} \nabla \\ &\leq \begin{pmatrix} \frac{\|\operatorname{Px} - \operatorname{Qx}\|_{g} + \|\operatorname{Bx} - \operatorname{Ty}\|_{g}}{\|\operatorname{Px} - \operatorname{By}\|_{g}} \end{pmatrix} \|\operatorname{Sx} - \operatorname{By}\|_{g} \\ &= \begin{pmatrix} \|\operatorname{Sx} - \operatorname{Ty}\|_{g} \nabla \|\operatorname{Px} - \operatorname{Sx}\|_{g} \nabla \|\operatorname{Qy} - \operatorname{By}\|_{g} \nabla \|\operatorname{Px} - \operatorname{Ty}\|_{g} \nabla \|\operatorname{Qy} - \operatorname{Sx}\|_{g} \nabla \\ &= \begin{pmatrix} \frac{\|\operatorname{Px} - \operatorname{Ax}\|_{g}\|\operatorname{Qy} - \operatorname{By}\|_{g}}{\|\operatorname{Px} - \operatorname{Qy}\|_{g}} \nabla \frac{\|\operatorname{Sx} - \operatorname{Ty}\|_{g}\|\operatorname{Qy} - \operatorname{Sx}\|_{g}}{\|\operatorname{Px} - \operatorname{Qy}\|_{g}} \end{pmatrix} \end{pmatrix} \end{split}$$

$$\|\mathbf{x} - \mathbf{y}\|_{g} \leq (\alpha + \beta) \|\mathbf{x} - \mathbf{y}\|_{g}$$

Which is contradiction. Thus x = y. This completes the proof of the theorem.

COROLLARY:

Let X be a G-Banach Space such that ∇ Satisfy α - property with $\alpha \leq 1$. If T be a mapping from X into itself, satisfying the following condition:

$$\left\| \mathbf{T}^{\mathbf{r}}\mathbf{x} - \mathbf{T}^{\mathbf{s}}\mathbf{y} \right\|_{\mathbf{g}}$$

$$\leq \alpha \max \begin{pmatrix} \|x - T^{s}y\|_{g} \|y - T^{r}x\|_{g} \nabla \frac{\|x - T^{r}x\|_{g} \|y - T^{s}y\|_{g}}{\|x - y\|_{g}} \nabla \frac{\|x - y\|_{g} \|y - T^{s}y\|_{g}}{\|y - T^{r}x\|_{g} + \|x - T^{r}x\|_{g}} \nabla \\ \left\{ \frac{\|x - T^{r}x\|_{g} + \|y - T^{s}y\|_{g}}{\|x - T^{s}y\|_{g}} \right\} \|x - T^{r}x\|_{g} \\ + \beta \max \begin{pmatrix} \|x - y\|_{g} \nabla \|x - T^{r}x\|_{g} \nabla \|y - T^{s}y\|_{g} \nabla \|x - T^{s}y\|_{g} \nabla \|y - T^{s}y\|_{g} \nabla \|y - T^{r}x\|_{g} \nabla \\ \frac{\|x - T^{r}x\|_{g} \|y - T^{s}y\|_{g}}{\|x - y\|_{g}} \nabla \frac{\|x - T^{r}x\|_{g} \|y - T^{r}x\|_{g}}{\|x - y\|_{g}} \end{pmatrix}$$

For non-negative α , β such that $0 < \alpha + \beta < 1$ and $r, s \in N$ (set of natural number). Then T has a unique common fixed point in X.

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